

Robustness and Recourse for the single period Open-Pit Problem with Processing Decision

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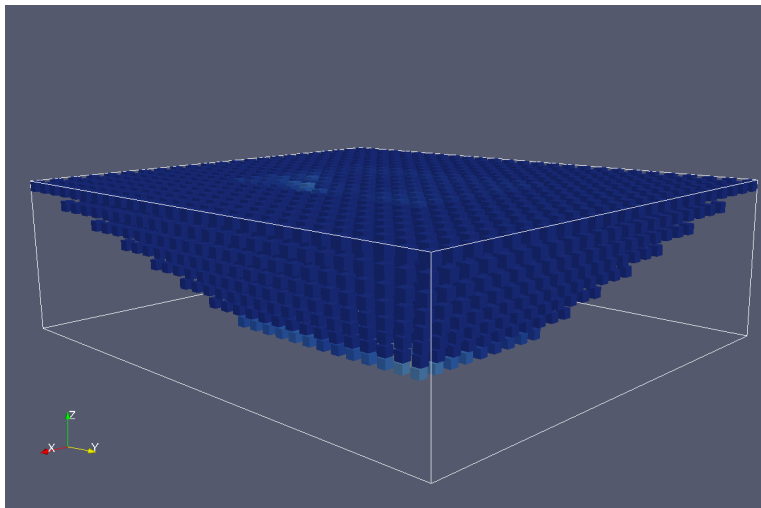
ACGO Seminar, August 2010

- 1 Extraction and Processing Problem
- 2 Robust models for Ore-Grade Uncertainty
 - Value-at-Risk (VaR) Model
 - Conditional Value-at-Risk (CVaR) Model
 - Modulated Convex-Hull Model
- 3 Computational Results
 - Mine 2 (15,910 blocks), N=10 samples
 - Mine 1 (2,728 blocks), N=50 samples
- 4 Conclusions & Discussion

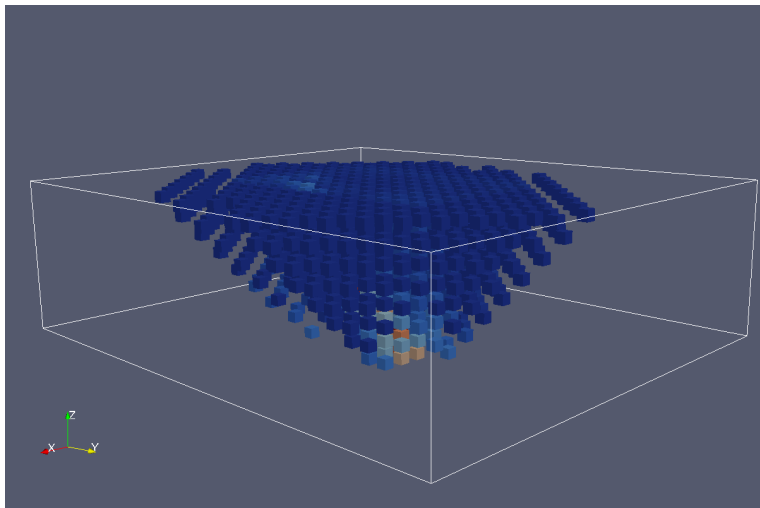
Open-Pit Mine (Chuquicamata, Chile)



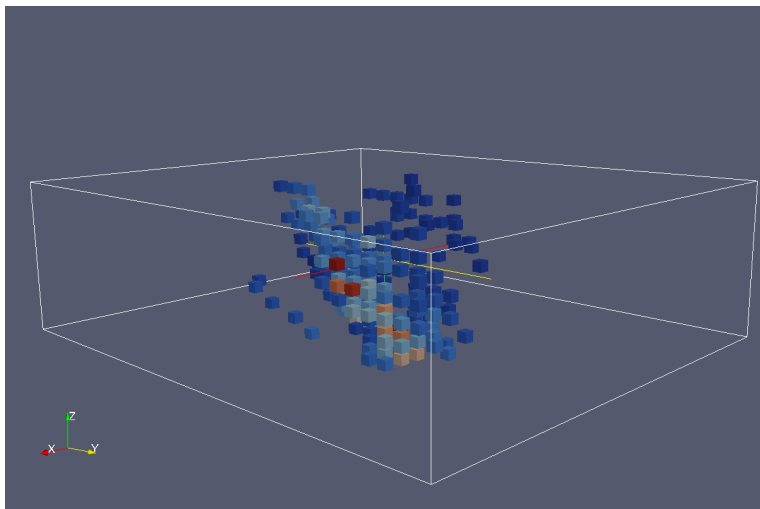
Set of blocks, colour \sim amount of mineral



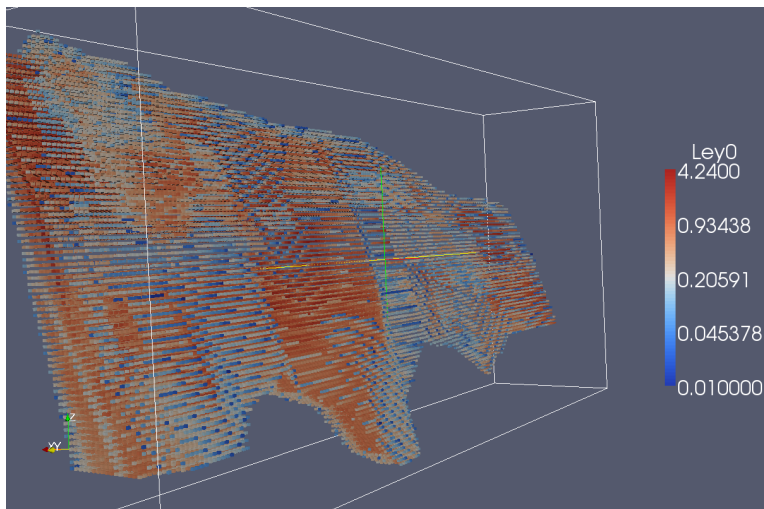
Which blocks extract?



From extracted ones, which blocks process?



Vein-type mine (medium size $\sim 700,000$ blocks)



Characteristics

- Open-pit mine
- Planning horizon: 1 period
- Production decision is divided in:
 - 1 Which blocks to extract
 - 2 Between the extracted blocks, which to process with *process 1*, which to process with *process 2*, and which not to process at all
- Processing is *exclusive*: each extracted block can be processed with *process 1* or with *process 2* but not with both

Formulation

Maximize Profit function:

$$\Pi_\rho(x^e, x^{\rho_1}, x^{\rho_2}) := \sum_{b \in \mathcal{B}} [\quad - v_b^e x_b^e \\ \quad + (w_b^{\rho_1} \rho_b - v_b^{\rho_1}) (x_b^{\rho_1} - x_b^{\rho_2}) \\ \quad + (w_b^{\rho_2} \rho_b - v_b^{\rho_2}) x_b^{\rho_2} \quad]$$

Subject to $(x^e, x^{\rho_1}, x^{\rho_2}) \in \{0, 1\}^{3 \cdot |\mathcal{B}|}$ is a factible extracting and processing plan:

$$\begin{array}{ll} x_a^e \leq x_b^e & \forall (a, b) \in \mathcal{P} \quad : \text{extr. precedences} \\ x_b^{\rho_2} \leq x_b^{\rho_1} \leq x_b^e & \forall b \in \mathcal{B} \quad : \text{exclusive pr.} \\ c^e \cdot x^e \leq B^e & : \text{extr. capacity} \\ c^{\rho_1} \cdot (x^{\rho_1} - x^{\rho_2}) \leq B^{\rho_1} & : \text{pr. 1 capacity} \\ c^{\rho_2} \cdot x^{\rho_2} \leq B^{\rho_2} & : \text{pr. 2 capacity} \end{array}$$

- Precedence-constrained 0-1 knapsack problem

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- We'll consider that the **ore grade of each block is an uncertain parameter**: $\tilde{\rho}_b$
 - This only affects profit function: $\Pi(x^e, x^{p_1}, x^{p_2}, \tilde{\rho})$
 - Π is affine linear in $\tilde{\rho}$
- We have joint ore grade distribution $(\tilde{\rho}_b)_{b \in \mathcal{B}} \rightsquigarrow \Lambda$ that can be sampled
- We have an i.i.d. sample of it:

$$\rho^1, \dots, \rho^N \quad \text{such that} \quad \mathbb{P}(\tilde{\rho} = \rho^i) = \frac{1}{N} \quad \forall i$$

- i.i.d. sampling supports covariance and weighted sampling
- We want to **compare** different approaches of **robustness to deal with uncertainty in the ore grades**

Value-at-Risk Model I

For a risk level $\epsilon \in [0, 1)$ (small) we'd like to solve the chance constrained model:

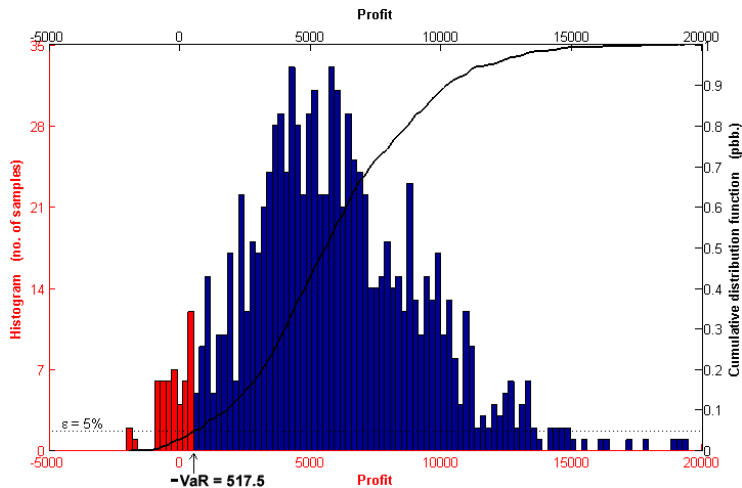
$$\begin{cases} \text{Max}_{x, \zeta} & \zeta \\ \text{s.t.} & \mathbb{P}_{\tilde{\rho}} [\Pi(x^e, x^{p_1}, x^{p_2}, \tilde{\rho}) \geq \zeta] \geq 1 - \epsilon \\ & (x^e, x^{p_1}, x^{p_2}) \in X, \quad \zeta \in \mathbb{R} \end{cases}$$

- Equivalent to minimize **Value-at-Risk** (VaR) of the Profit Π

$$\text{VaR}_\epsilon(Y) := -\text{Max} \{ t \in \mathbb{R} : \mathbb{P}(Y \geq t) \geq 1 - \epsilon \} = -(\epsilon\text{-percentile for } Y)$$

- (Approximation) Formulation: MILP with “Big-M”
- Sampled approximation is consistent under *mild* assumptions

Value-at-Risk Model II



Processing decision as a Recourse variable

We'd also like to consider the next decision scheme:

- 1 We first decide which blocks to **extract**
- 2 Once extracted, **we can see the real ore grade** of each extracted block
- 3 We then decide **which extracted blocks to process** and how

So, basically, the **processing decision is a *Recourse variable***

- Formulation: put one processing decision per scenario
- Recourse variant of VaR model is also consistent

Conditional Value-at-Risk Model I

Conditional Value-at-Risk (CVaR) for risk level $\epsilon \in (0, 1]$:

- If Y (profits) has atomless distribution,

$$\text{CVaR}_\epsilon(Y) := -\mathbb{E}\left[Y \mid Y \leq \underbrace{-\text{VaR}_\epsilon(Y)}_{\epsilon\text{-percentile for } Y} \right]$$

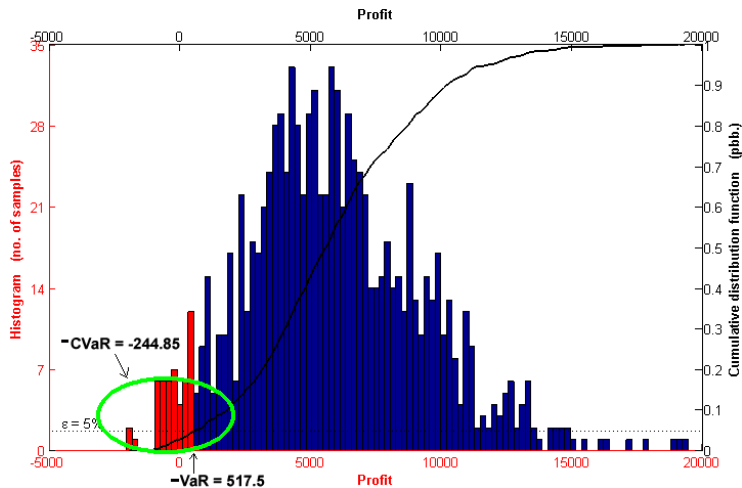
- CVaR model:

$$\begin{cases} \min & \text{CVaR}_\epsilon [\Pi(x^e, x^{p1}, x^{p2}, \tilde{\rho})] \\ \text{s. t.} & (x^e, x^{p1}, x^{p2}) \in X \end{cases}$$

Has MILP formulation. Model with recourse too.

- ! Case $\epsilon = 1$ equivalent to $\text{Max}_{(x^e, x^{p1}, x^{p2}) \in X} \mathbb{E} [\Pi(x^e, x^{p1}, x^{p2}, \tilde{\rho})]$
- Sampled approximation, with and w/o recourse, **is consistent.**

Conditional Value-at-Risk Model II



Modulated Convex-Hull Model I

We propose the next *uncertainty-set based* robust model:

$$\begin{cases} \text{Max}_x & \min_{\rho \in \mathcal{U}_\epsilon} \Pi(x^e, x^{\rho_1}, x^{\rho_2}, \rho) \\ \text{s. t.} & (x^e, x^{\rho_1}, x^{\rho_2}) \in X \end{cases}$$

where $\epsilon \in [0, 1]$ is a desired risk level and

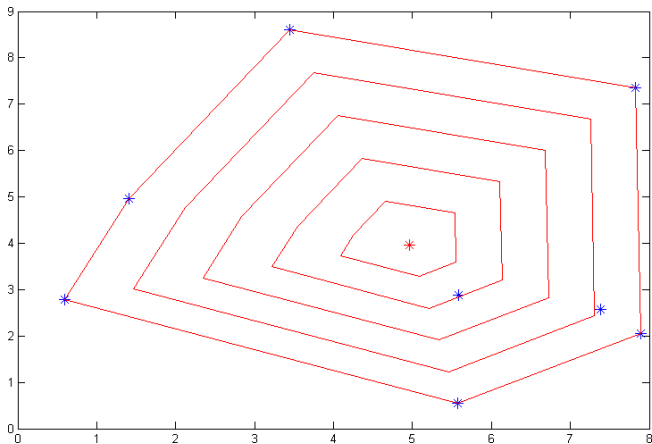
$$\mathcal{U}_\epsilon = \bar{\rho} + (1 - \epsilon) \left(\text{conv} \{ \rho^1 \dots \rho^N \} - \bar{\rho} \right)$$

- Has MILP formulation. Model with Recourse too.

! Case $\epsilon = 1$ equivalent to $\text{Max}_{(x^e, x^{\rho_1}, x^{\rho_2}) \in X} \mathbb{E} [\Pi(x^e, x^{\rho_1}, x^{\rho_2}, \tilde{\rho})]$

Modulated Convex-Hull Model II

Example: \mathcal{U}_ϵ for $N = 8$ samples of $\tilde{\rho} \in \mathbb{R}^2$



Modulated Convex-Hull Model III

Proposition: Mod. Convex Hull as risk averse optimization

1

$$\begin{aligned} & \max_{(x^e, x^{p1}, x^{p2}) \in X} \min_{\rho \in \mathcal{U}_\epsilon} \Pi(x^e, x^{p1}, x^{p2}, \rho) \\ \iff & \min_{(x^e, x^{p1}, x^{p2}) \in X} \mu_{\epsilon, N}(\Pi(x^e, x^{p1}, x^{p2}, \tilde{\rho})) \end{aligned}$$

where $\mu_{\epsilon, N}$ is the risk measure

$$\mu_{\epsilon, N}(Z) = (1 - \epsilon) \underbrace{\mathbb{E}(-Z)}_{\text{CVaR}_1(Z)} + \epsilon \underbrace{\max_{i=1 \dots N} \{-Z(\omega^i)\}}_{\text{CVaR}_{\frac{1}{N}}(Z)}$$

for Z r.v. in the equiprobable space $\Omega = \{\omega^1 \dots \omega^N\}$

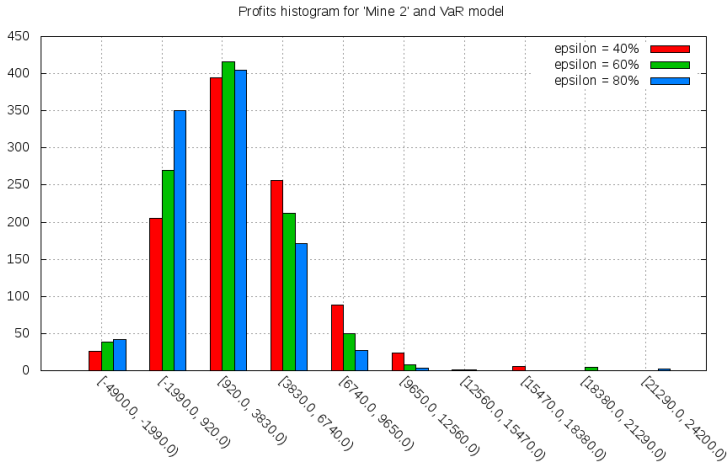
2

$\mu_{\epsilon, N}$ is a *distortion risk measure*: it's a *coherent risk measure*, *comonotonic* and *law invariant*.

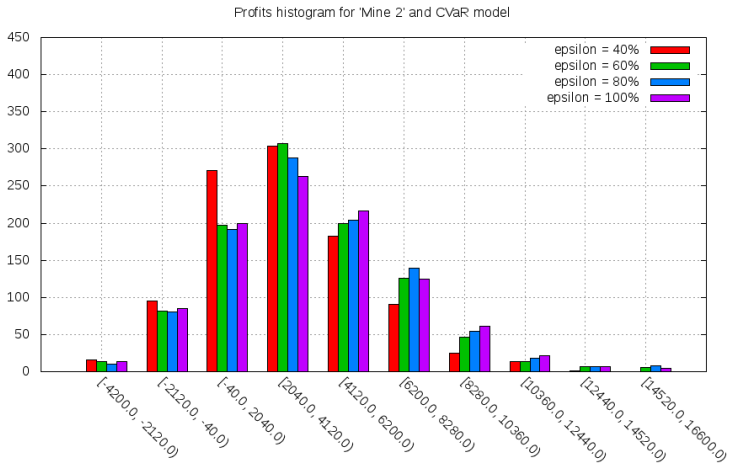
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- We consider two vein-type mines, only one process available
- For each mine we have 1000 possible scenarios for the grades
- We take a random sample of $N = 10, 20, \dots$ out of the 1000 possible grade scenarios,
- and for risk levels $\epsilon = 10\%, 20\%, \dots, 100\%$ we solve the robust models. We obtain a production plan x^{e*}, x^{ρ_1*} per model.
- For each model, risk level ϵ and sample size N we present the distribution of the profits:
empiric distribution for $\Pi(x^{e*}, x^{\rho_1*}, \rho^k) \quad k = 1 \dots 1000$

VaR model performance

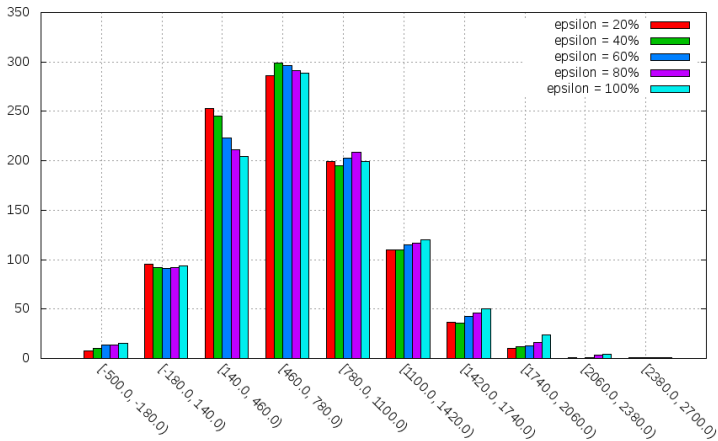


CVaR model performance

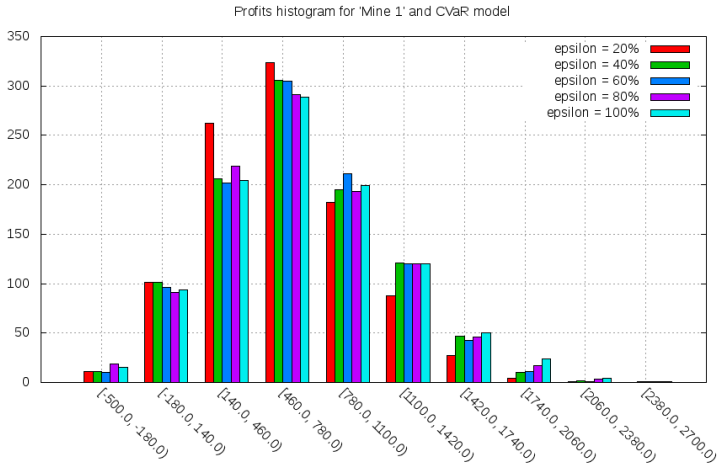


Modulated Convex-Hull model

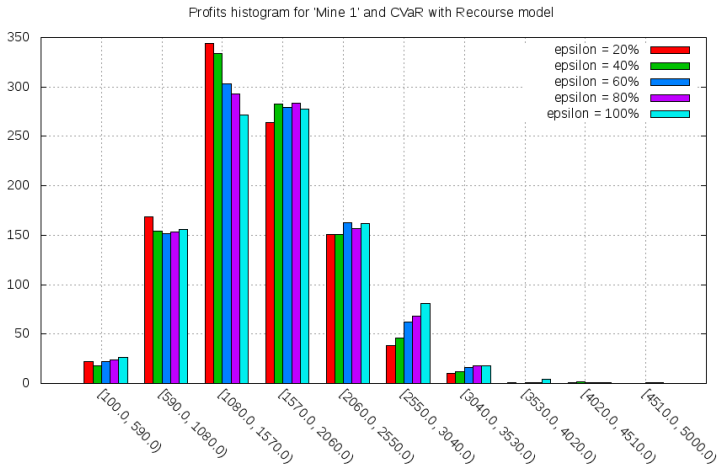
Profits histogram for 'Mine 1' and Mod. Convex-Hull model



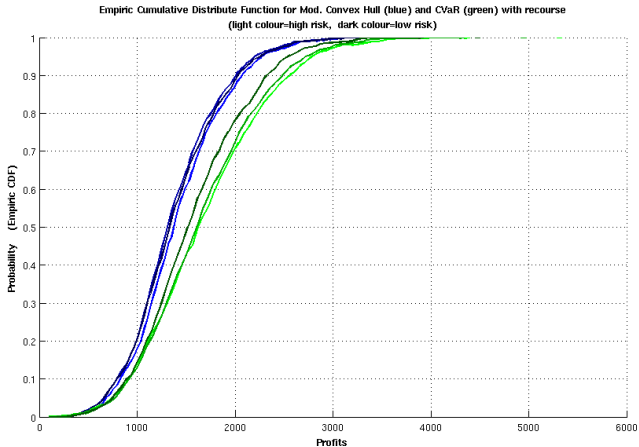
CVaR model results



CVaR with Recourse model results



Mod. Convex Hull & CVaR models with Recourse






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Conclusions & Discussion

- CVaR performs considerably better than VaR in this problem
- Mod. Convex Hull model performs similar to CVaR, although they're motivated by different schemes
- Value of information: taking processing variables as recourse variables has considerable benefits
- In recourse models, CVaR shows a “more coherent” behaviour than Mod. Convex Hull
- Validation of Mod. Convex Hull model: for $\tilde{\rho}, \rho^1 \dots \rho^N$ i.i.d., what is $\mathbb{P} [\tilde{\rho} \in \text{conv} \{\rho^1 \dots \rho^N\}]$?

Bibliography

-  Bertsimas, D. & D. Brown (2009)
Constructing Uncertainty Sets for Robust Linear Optimization
-  Rockafellar, R. & S. Uryasev (2002)
Conditional Value-at-Risk for General Loss Distributions
-  Shapiro, A., D. Dentcheva & A. Ruszczyński (2009)
Lectures on Stochastic Programming-Modeling and Theory

Formulation of deterministic problem

$$\begin{cases} \text{Max} & \Pi(x^e, x^{p_1}, x^{p_2}, \rho) \\ \text{s.t.} & (x^e, x^{p_1}, x^{p_2}) \in X \end{cases}$$

- ~ $3|\mathcal{B}|$ binary variables
- ~ $|\mathcal{P}| + 2|\mathcal{B}| + 3$ restrictions

S.A.A. formulation of Value-at-Risk model

$$\left\{ \begin{array}{l}
 \text{Max}_{x, z, \zeta} \quad \zeta \\
 \text{s.t.} \quad \Pi(x^e, x^{p_1}, x^{p_2}, \rho^k) + z_k M^k \geq \zeta \quad \forall k = 1 \dots N \\
 \sum_{k=1}^N z_k \leq \lfloor N\epsilon \rfloor \\
 z_k \in \{0, 1\}^N \quad \forall k = 1 \dots N \\
 \zeta \in \mathbb{R} \\
 (x^e, x^{p_1}, x^{p_2}) \in X
 \end{array} \right.$$

for sufficiently big $M^k \in \mathbb{R}$ parameter

- + N binary variables & 1 continuum variable
- + $(N + 1)$ restrictions

S.A.A. formulation of Conditional Value-at-Risk model

$$\left\{ \begin{array}{l} \min_{x, \zeta, \eta} \quad \zeta + \frac{1}{N\epsilon} \sum_{k=1}^N \eta_k \\ \text{s.t.} \quad \Pi(x^e, x^{\rho_1}, x^{\rho_2}, \rho^k) + \zeta + \eta_k \geq 0 \quad \forall k = 1 \dots N \\ \quad \eta_k \geq 0 \quad \forall k = 1 \dots N \\ \quad \zeta \in \mathbb{R} \\ \quad (x^e, x^{\rho_1}, x^{\rho_2}) \in X \end{array} \right.$$

- + $(N + 1)$ continuum variables
- + $2N$ restrictions

S.A.A. formulation of Mod. Convex-Hull model

$$\left\{ \begin{array}{l} \text{Max}_{x, \zeta} \quad \zeta \\ \text{s.t.} \quad \Pi(x^e, x^{\rho_1}, x^{\rho_2}, \bar{\rho} + (1 - \epsilon)(\rho^k - \bar{\rho})) \geq \zeta \quad \forall k = 1 \dots N \\ \quad \quad \zeta \in \mathbb{R} \\ \quad \quad (x^e, x^{\rho_1}, x^{\rho_2}) \in X \end{array} \right.$$

- + 1 continuum variable
- + N restrictions

Consistency of S.A.A. for VaR model

Proposition 5.30, [SPBook]

If there exists a solution $(x^{e*}, x^{p1*}, x^{p2*}, \zeta^*)$ for the real problem

$$\theta^* := \begin{cases} \text{Max}_{x, \zeta} & \zeta \\ \text{s.t.} & \mathbb{P}_{\tilde{\rho}} [\Pi(x^e, x^{p1}, x^{p2}, \tilde{\rho}) \geq \zeta] \geq 1 - \epsilon \\ & (x^e, x^{p1}, x^{p2}) \in X, \quad \zeta \in \mathbb{R} \end{cases}$$

such that $\forall \epsilon > 0$ there exists a factible solution $(x^e, x^{p1}, x^{p2}, \zeta)$ to the true problem that satisfies

- $\| (x^e, x^{p1}, x^{p2}, \zeta) - (x^{e*}, x^{p1*}, x^{p2*}, \zeta^*) \| \leq \epsilon$
- $\mathbb{P}_{\tilde{\rho}} [\Pi(x^e, x^{p1}, x^{p2}, \tilde{\rho}) \geq \zeta] > 1 - \epsilon$

then the approximated estimator is consistent and the distance between the set of optimal solutions of the approximated problem and the optimal solutions of the true problem tends to 0.